

Advanced Control Systems Detection, Estimation, and Filtering

***Graduate Course on the
MEng PhD Program
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Chapter 2 Minimum Variance Unbiased Estimation

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Syllabus:

Classical Estimation Theory

Chap. 1 - **Motivation for Estimation in Stochastic Signal Processing** [1/2 week] Motivating examples of signals and systems in detection and estimation problems;

Chap. 2 - **Minimum Variance Unbiased Estimation** [1/2 week]

Unbiased estimators; Minimum Variance Criterion; Extension to vector parameters; Efficiency of estimators;

Chap. 3 - **Cramer-Rao Lower Bound** [1 week]

Estimator accuracy; Cramer-Rao lower bound (CRLB); CRLB for signals in white Gaussian noise; Examples;

continues...

Unbiased estimators:

The search for good estimators for unknown deterministic parameters begins

Example (revisited):

Unbiased estimator for DC level in white Gaussian noise. Signal model is

$$x[n] = A + w[n] \quad n = 0, 1, \dots, N-1$$

A reasonable estimator is $\hat{A} = k \frac{1}{N} \sum_{n=0}^{N-1} x[n]$

Due to the linearity properties of the expectation operator $E[.]$:

$$E \left[\hat{A} \right] = E \left[k \frac{1}{N} \sum_{n=0}^{N-1} x[n] \right] = k \frac{1}{N} \sum_{n=0}^{N-1} E[x[n]] = k \frac{1}{N} NA = kA$$

Unbiased estimator iff $k=1$!

Unbiasness:

Let the vector of deterministic unknown parameters, with p components, be described as

$$\theta = \begin{bmatrix} \theta_1 \\ \theta_2 \\ \vdots \\ \theta_p \end{bmatrix} = [\theta_1 \quad \theta_2 \quad \dots \quad \theta_p]^T$$

An estimator must have the same dimensions, i.e.

$$\hat{\theta} = \begin{bmatrix} \hat{\theta}_1 \\ \hat{\theta}_2 \\ \vdots \\ \hat{\theta}_p \end{bmatrix} = [\hat{\theta}_1 \quad \hat{\theta}_2 \quad \dots \quad \hat{\theta}_p]^T$$

The estimator is **unbiased** iff

$$E[\hat{\theta}] = \theta$$

Minimum variance criterion:

In searching for estimators some optimality criterion must be adopted.

A natural one is the **mean square error (MSE)**, defined as

$$mse(\hat{\theta}) = E \left[(\hat{\theta} - \theta)^2 \right]$$

Unfortunately the choice of the criterion leads to unrealizable estimators, i.e. not only function of the data

$$\begin{aligned} mse(\hat{\theta}) &= E \left\{ \left[(\hat{\theta} - E[\hat{\theta}]) + (E[\hat{\theta}] - \theta) \right]^2 \right\} = \text{var}(\hat{\theta}) + \left[(E[\hat{\theta}] - \theta) \right]^2 = \\ &= \text{var}(\hat{\theta}) + b^2(\theta), \quad \text{where } b^2(\theta) = E[\hat{\theta}] - \theta. \end{aligned}$$

Fortunately, after differentiation an estimator depending on θ will result.

Minimum variance criterion:

Example:

Find the value of k such that a realizable mse estimator results

$$x[n] = A + w[n] \quad n = 0, 1, \dots, N-1, \quad \hat{A} = k \frac{1}{N} \sum_{n=0}^{N-1} x[n]$$

From the previous page

$$\text{var}(\hat{A}) = \frac{k^2 \sigma^2}{N}, \quad \text{and} \quad b^2(A) = E[\hat{A}] - A = (kA - A)^2$$

$$\text{mse}(\hat{A}) = \text{var}(\hat{A}) + b^2(A) = \frac{k^2 \sigma^2}{N} + (k-1)^2 A^2$$

Lets find the minimum

$$\frac{d}{dk} \text{mse}(\hat{A}) = \frac{2k\sigma^2}{N} + 2(k-1)A^2 = 0, \quad \text{results in} \quad k_{opt} = \frac{A^2}{A^2 + \sigma^2 / N}$$

Unfortunately depends on the unknown parameter A .

Minimum variance unbiased estimator:

The Minimum Variance Unbiased (MVU) Estimator **must have** smallest variance for all values of θ .

In general, the MVU estimator does not always exist.

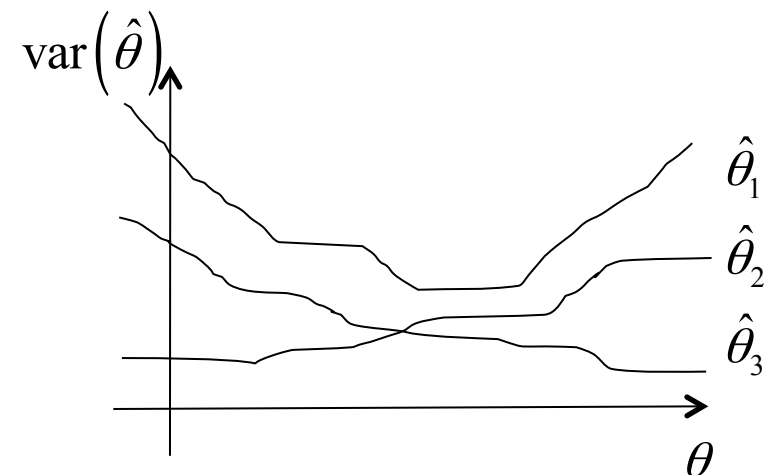
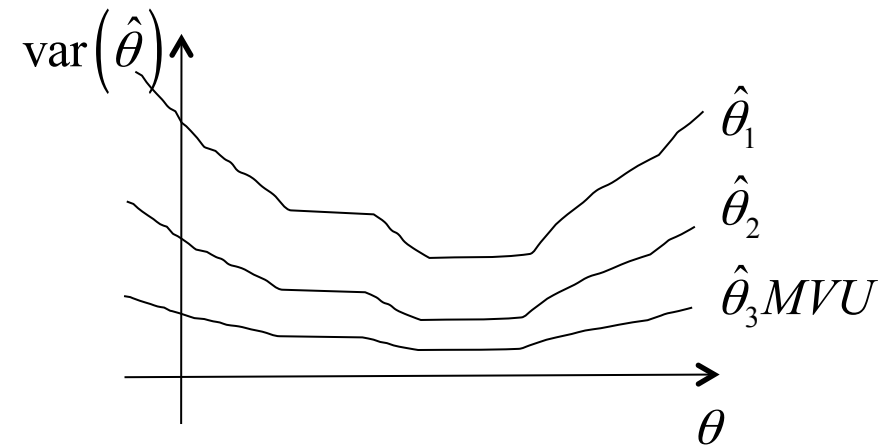
There is no “turn-the-crank” method.

Future approaches:

Chp. 3 – Cramer-Rao lower bound

Chp. 5 – Sufficient statistics

Chp. 6 – Restrict to linear estimators: BLUE



Bibliography:

Further reading

- Harry L. Van Trees, ***Detection, Estimation, and Modulation Theory, Parts I to IV***, John Wiley, 2001.
- J. Bibby, H. Toutenburg, ***Prediction and Improved Estimation in Linear Models***, John Wiley, 1977.
- C.Rao, ***Linear Statistical Inference and Its Applications***, John Wiley, 1973.
- P. Stoica, R. Moses, “*On Biased Estimators and the Unbiased Cramer-Rao Lower Bound*,” *Signal Process*, vol.21, pp. 349-350, 1990.