Industrial Automation

(Automação de Processos Industriais)

GRAFCET (Sequential Function Chart)

http://www.isr.ist.utl.pt/~pjcro/courses/api1011/api1011.html

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Syllabus:

Chap. 3 – PLCs Programming Languages [2 weeks]

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Chap. 4 - GRAFCET (Sequential Function Chart) [1 week]

The GRAFCET norm.

Elements of the language.

Modelling techniques using GRAFCET.

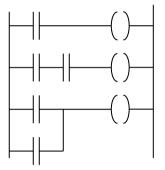
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Chap. 5 – CAD/CAM and CNC Machines [1 week]

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PLCs Programming Languages (IEC 1131-3)

Ladder Diagram



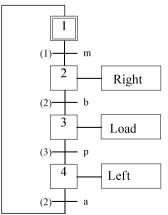
Structured Text

If %I1.0 THEN
%Q2.1 := TRUE
ELSE
%Q2.2 := FALSE
END_IF

Instruction List

LD %M12 AND %I1.0 ANDN %I1.1 OR %M10 ST %Q2.0

Sequential Function Chart (GRAFCET)



Some pointers to GRAFCETs (SFCs)

History: http://www.ecsi.org/ecsi/Doc/OtherDoc/SLDL/PDF/caspi.pdf

http://www.lurpa.ens-cachan.fr/grafcet/groupe/gen_g7_uk/geng7.htm

Tutorial: http://asi.insa-rouen.fr/~amadisa/grafcet-homepage/tutorial/index.html

http://www-ipst.u-strasbg.fr/pat/autom/grafce t.htm

Simulator: http://asi.insa-rouen.fr/~amadisa/grafcet-homepage/grafcet.html

http://www.automationstudio.com (See projects)

Bibliography: * Petri Nets and GRAFCET: Tools for Modelling Discrete Event Systems

R. DAVID, H. ALLA, New York: PRENTICE HALL Editions, 1992

* Programação de Autómatos, Método GRAFCET, José Novais,

Fundação Calouste Gulbenkian

* Norme Française NF C 03-190 + R1 : Diagramme fonctionnel

"GRAFCET" pour la description des systèmes logiques de commande

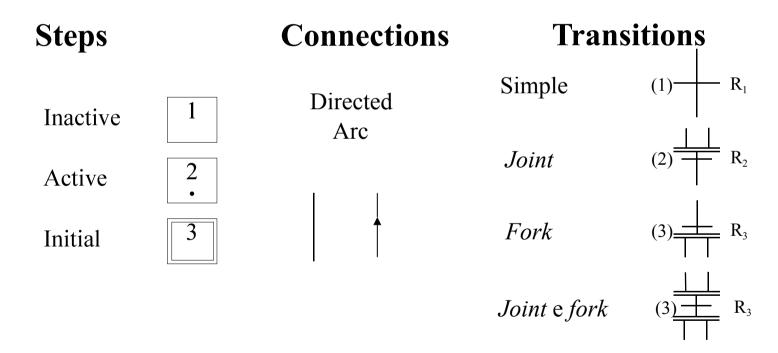
Homepage: http://www.lurpa.ens-cachan.fr/grafcet/

History

GRAFCET

- 1975 Decision of the workgroup "Logical Systems" da AFCET (Association Française de Cybernétique Economique et Technique) on the creation of a committee to study a standard for the representation of logical systems and automation.
- 1977 GRAFCET definition (Graphe Fonctionnel de Commande Etape-Transition).
- 1979 Dissemination in schools and adopted as research area for the implementation of solutions of automation in the industry.
- 1988 GRAFCET becomes an international standard denominated as "Sequential Function Chart", pela I.E.C.

Basic Elements



Actions can be associated with Steps.

A logical receptivity function can be associated with each **Transition**.

Basic Elements

Oriented connections (arcs)

In a GRAFCET:

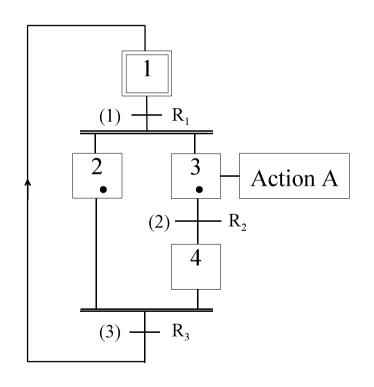
An Arc can connect Steps to Transitions

An Arc can connect Transitions to Steps

A Step can have no Transitions as inputs (source);

A Step can have no Transitions as outputs (drain);

The same can occur for the Transitions.

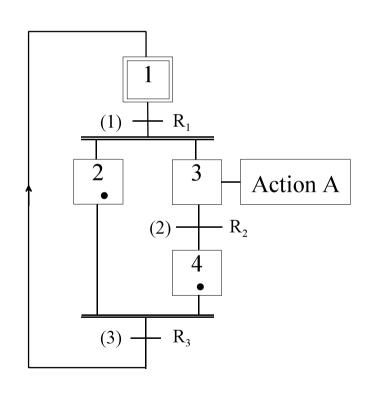


State of a GRAFCET

The set of markings of a GRAFCET constitutes its state.

Question:

How evolves the state of a GRAFCET?



State Evolution:

• Rule 1: Initial State

It is characterized by the active Steps at the beginning of operation (at least one).

• Rule 2: Transposition of a Transition

A Transition is active or enabled only if all the Steps at its input are active (if not it is inactive).

A Transition can only be transposed if it is active and its associated condition is true (receptivity function).

• Rule 3: Evolution of active Steps

The transposition of a Transition leads to the deactivation of all the Steps on its inputs and the activation of all Steps on its outputs.

• Rule 4: Simultaneous transposition of Transitions

All active Transitions are transposed simultaneously.

• Rule 5: Simultaneous activation and deactivation of a Step

In this case the activation has priority.

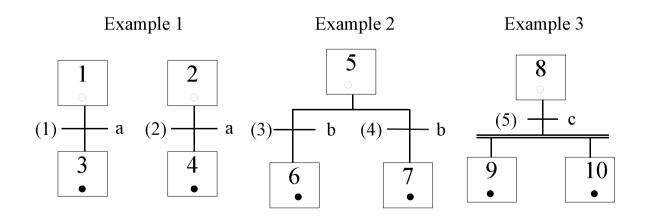
State Evolution:

• Rule 2a:

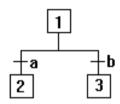
All active Transitions are transposed immediately.

• Rule 4:

Simultaneous active Transitions are transposed simultaneously.



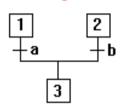
OR Divergences:



If Step 1 is active and if **a** is TRUE then Step 1 is deactivated and Step 2 is activated (state of Step 3 is maintained).

If **a** and **b** are TRUE and Step 1 is active then Step 1 is deactivated and Steps 2 and 3 are activated (for any previous state of Steps 2 and 3).

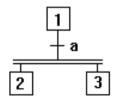
OR Convergences:



If Step 1 is active and if **a** is TRUE then Step 1 is deactivated and Step 3 is activated (state of Step 2 remains unchanged). The same happens for Step 2 and **b**.

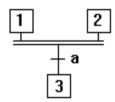
If both Steps 1 and 2 are active and **a** and **b** are TRUE then Steps 1 and 2 are deactivated and Step 3 is activated.

AND Divergences:



If Step 1 is active and if **a** is TRUE then Step 1 is deactivated and Steps 2 and 3 are activated.

AND Convergences:

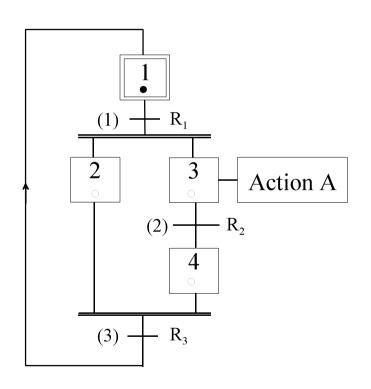


If Steps 1 and 2 are active and if **a** is TRUE then Steps 1 and 2 are deactivated and Step 3 is activated (if only one of the input steps is active, the state remains).

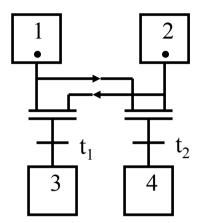
Example:

GRAFCET state evolution

Level activated Action. Actions can also be activated during transitions - see next.



Modelling problem:



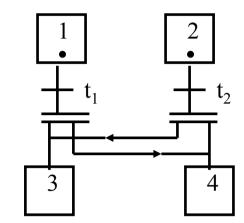
Given 4 Steps (1 to 4) and 2 Transitions (t1 and t2) write a segment of GRAFCET to solve the following problem:

In the case that the Steps 1 and 2 are active:

- if t1 is TRUE, activate Step 3 (and deactivate Steps 1 and 2);
- if t2 is TRUE, activate Step 4 (and deactivate Steps 1 and 2);
- otherwise, the state is maintained.

Other modelling problem:

Given 4 Steps (1 to 4) and 2 Transitions (t1 and t2) write a segment of GRAFCET to solve the following problem:



If Step 1 is active and t1 is TRUE

OR

If Step 2 is active and t2 is TRUE

THEN

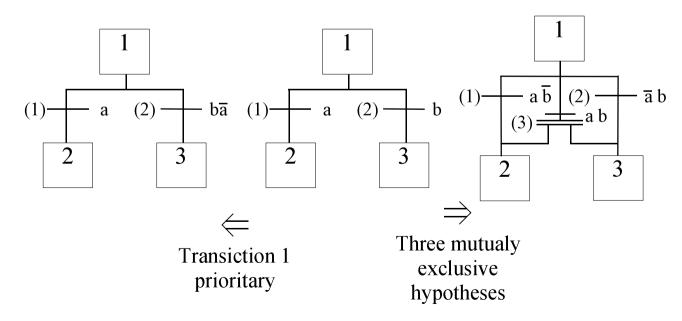
Activate Steps 3 and 4.

GRAFCET state evolution:

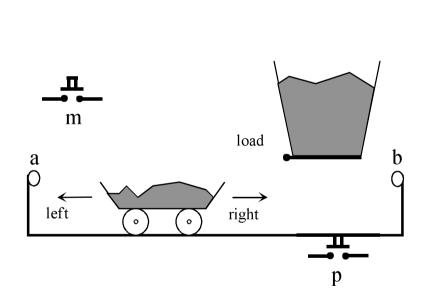
Conflicts:

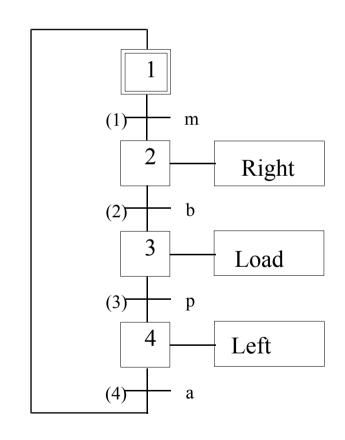
There exist Conflicts when the validation of a Transition depends on the same Step or when more than one receptivity functions can become true simultaneously.

Solutions:

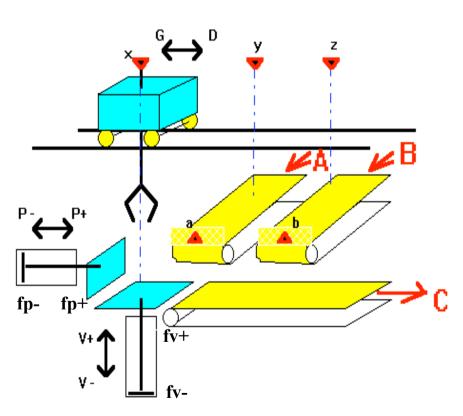


Example: modeling a control/automation system



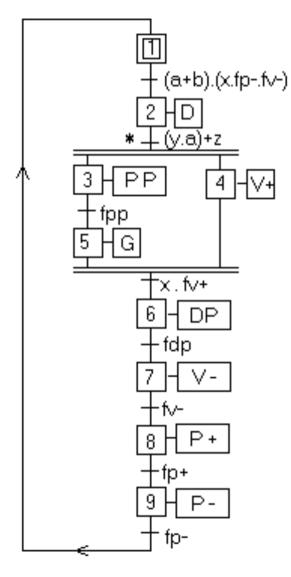


Example: modeling a automated transport workcell

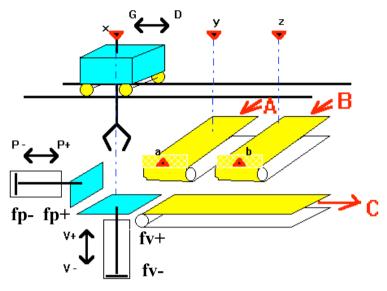


- * Conveyor A, with sensor a to detect the existence of part;
- * Conveyor **B**, with sensor **b** to detect the existence of part;
- •Manipulator on linear base commands **D** (droit) e **G** (gauche), Sensors **x**, **y** e **z** to detect manipulator on base, over A, and over B, respectively.
- •Clamp with command to grab partt **PP**, and a limit switch (**fpp**). To unload part receives command **DP** and two limit Switches detect extremes of operation **fv**+ on top and and **fv** down.
- * Efector to push parts with commands **P**+ e **P**-, And two limit switches **fp**+ e **fp**-.
- * The output conveyor is always ON.
- *Conveyors A e B are commanded by other automata, independent of this workcell.

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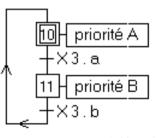
Solution:



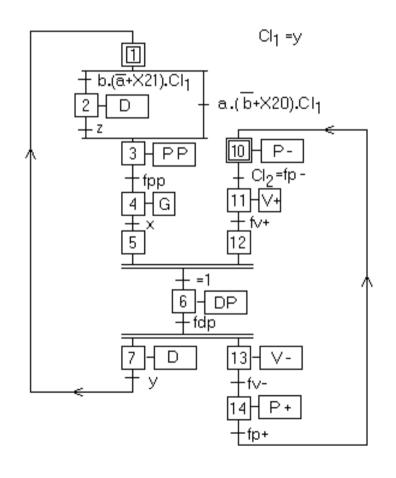
To guarantee alternate priorities, modify the programm with receptivity funcion (*) $y.a.(\overline{b}+\times10)+z$

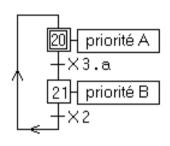
Meaning: grag part in **y**, if there exists part in **a** and if b is not prioritary; otherwise continue, stopping **b**.

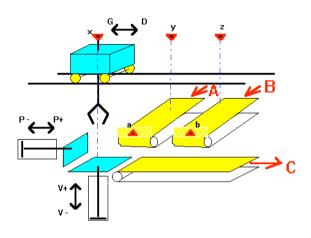
To implement the priorities add the following GRAFCET:



Improved solution:







- a)After part is processed search next;
- b) Optimize the base of the manipulator to reduce delays –

obvious solution: y.

Example: modeling and automation of a distribution system

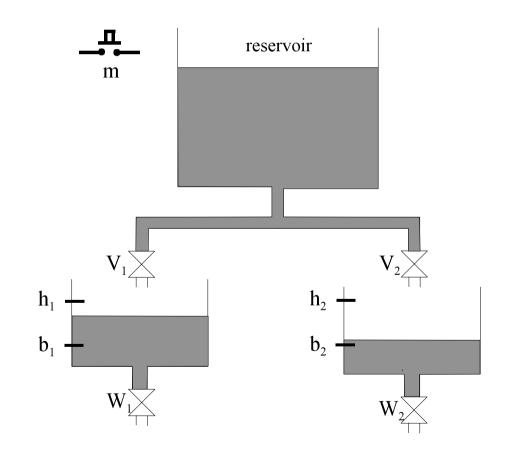
Sensors:

 \mathbf{m}

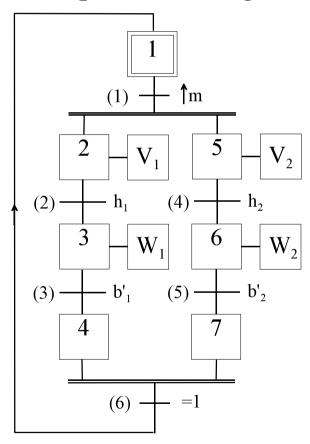
b₁, h₁, b₂ e h₂

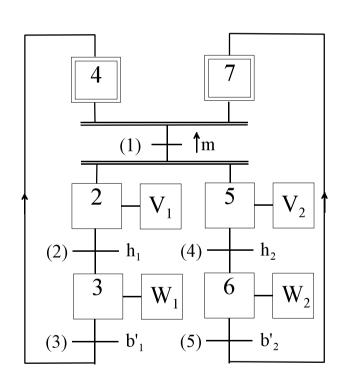
Actuators:

V₁, V₂, W₁ e W₂

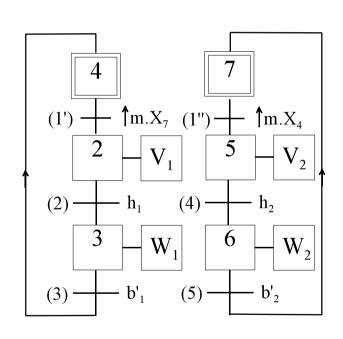


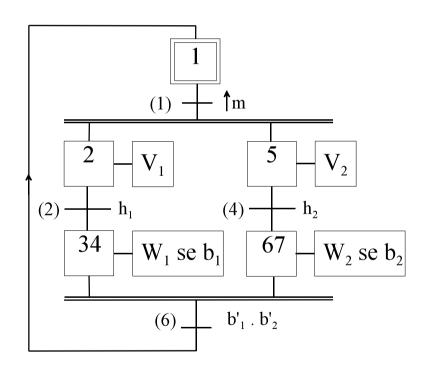
Example: modeling and automation of a distribution system





Example: modeling and automation of a distribution system





Events: Properties

$$\uparrow a \cdot a = \uparrow a$$
 $\uparrow a \cdot a' = 0$ $\forall a \cdot a' = \forall a \cdot a = 0$

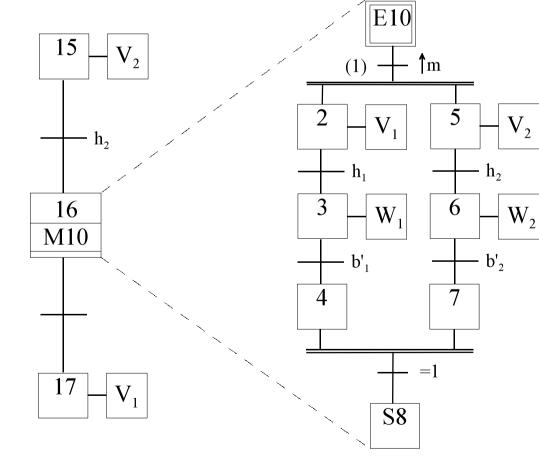
$$\uparrow$$
(a · b) = \uparrow a · b + \uparrow b · a \uparrow (a + b) = \uparrow a · b' + \uparrow b · a'

$$\uparrow$$
(a.b). \uparrow (a.c) = \uparrow (a.b.c)

in general, if events a and b are independents

$$\uparrow a \cdot \uparrow b = 0$$

Other auxiliary mechanisms



Macro-steps

Other auxiliary mechanisms

Pseudo Macro-steps

Macro Actions

- Force actions
- Enable actions
- Mask actions

Implementation in DOLOG80

The activity of each Step is stored in an auxiliary memory.

At startup do:	Store R _k eva	luation in M100	
AM128			
SLMx	AM1		
•••	AM2	AM3	
AM128	AM100	AM4	
SLMy	SLM3	RLM1	$(k) \longrightarrow R_k$
(initial steps)	AM1	AM3	
RLM128	AM2	AM4	$\begin{bmatrix} 1 \\ 3 \end{bmatrix} \begin{bmatrix} 1 \\ 4 \end{bmatrix}$
	AM100	RLM2	
	SLM4		

Implementation in the TSX3722/TSX57

Steps

Name	Symbol	Functions
Initial steps (i ou i	symbolize the initial active steps at the beginning of the cycle after initialization or re-start from cold.
Simple steps (i ou i	show that the automatic system is in a stable condition. The maximum number of steps (including the initial steps) can be configured from: 1 - 96 for a TSX 37-10, 1 - 128 for a TSX 37-20, 1 - 250 for a TSX 57. The maximum number of active steps at the same time can be configured.

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Implementation in the TSX3722/TSX57

Macro-steps

Name	Symbol	Functions
Macro steps	i	Symbolize a macro step: a single group of steps and transitions. The maximum number of macro steps can only be configured from 0 - 63 for the TSX 57.
Stage of Macro steps	i ou i IN ou OUT	Symbolizes the stages of a macro step. The maximum number of stages for each macro step can be configured from 0 - 250 for the TSX 57. Each macro step includes an IN and OUT step.

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Name	Symbol	Functions
Transitions	+	allow the transfer from one step to another. A transition condition associated with this condition is used to define the logic conditions necessary to cross this transition. The maximum number of transitions is 1024. It cannot be configured. The maximum number of valid transitions at the same time can be configured.
AND divergences	+	Transition from one step to several steps: is used to activate a maximum of 11 steps at the same time.
AND convergences	+	Transition of several steps to one: is used to deactivate a maximum of 11 steps at the same time.
OR divergences	+ +	Transition from one step to several steps: is used to carry out a switch to a maximum of 11 steps.
OR convergences	+ +	Transition of several steps to one: is used to end switching from a maximum of 11 steps.

Implementation in the TSX3722/TSX57

Arcs/Connectors

Name	Symbol	Functions
Source connectors	n	"n" is the number of the step "it comes from" (source step).
Destination con- nector) n	"n" is the number of the step "it's going to" (target step).
Links directed towards: • top • bottom • right or left	<u></u>	These links are used for switching, jumping a step, restarting steps (sequence).

Information associated with Steps in the GRAFCET:

Name		Description	
Bits associated	%Xi	Status of the i step of the main Grafcet	
with the steps (1		(i from 0 - n) (n depends on the processor)	
= active step)	%XMj	Status of the j macro step (j from 0 - 63 for TSX/PMX/PCX 57)	
	%Xj.i	Status of the i step of the j macro step	
	%Xj.IN	Status of the input step of the j macro step	
	%Xj.OUT	Status of the output step of the j macro step	
System bits as-	%S21	Initializes Grafcet	
sociated with	%S22	Grafcet resets everything to zero	
Grafcet	%S23	Freezes Grafcet	
	%S24	Resets macro steps to 0 according to the system words %SW22 - %SW25	
	%S25	 Set to 1 when: tables overflow (steps/transition), an incorrect graph is run (destination connector on a step which does not belong to the graph). 	

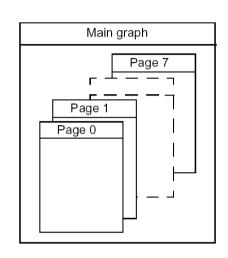
Information associated with Steps in the GRAFCET (bis):

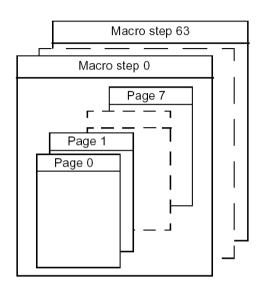
Name		Description
Words associat-	%Xi.T	Activity time for main Grafcet step i.
ed with steps	%Xj.i.T	Activity time for the i step of the j macro step
	%Xj.IN.T	Activity time for the input step of the j macro step
	%Xj.OUT.T	Activity time for the output step of the j macro step
System words associated with	%SW20	Word which is used to inform the current cycle of the number of active steps, to be activated and deactivated.
Grafcet	%SW21	Word which is used to inform the current cycle of the number of valid transitions to be validated or invalidated.
	%SW22 à %SW25	Group of 4 words which are used to indicate the macro steps to be reset to 0 when bit %S24 is set to 1.

And where to find information related with Transitions?

Does not make sense state or activity nor timmings (only number of occurences).

General structure:





Number	TSX 37 -10	TSX 37 -10		TSX 37 -20		TSX 57	
	Default settings	Maxi- mum	Default settings	Maxi- mum	Default settings	Maxi- mum	
Main graph steps	96	96	128	128	128	250	
Macro steps	0	0	0	0	8	64	
Macro step steps	0	0	0	0	64	250	
Step total	96	96	128	128	640	1024	
Steps active at the same time	16	96	20	128	40	250	
Transitions valid at the same time	20	192	24	256	48	400	

Editor: 8 páginas

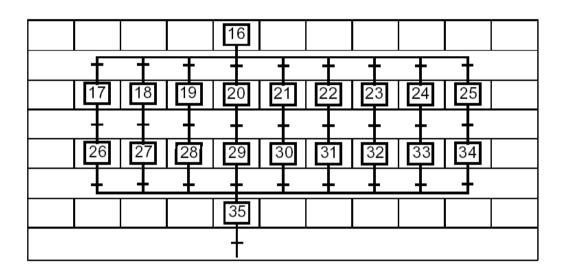
- Pages 0 to 7
- 154 cells (14*11)

1 2 3 4 5 6 7 8 9 10 11 1 2 0</td

- The first line is used to enter the source connectors.
- The last line is used to enter the destination connectors.
- The even lines (from 2 12) are step lines (for destination connector steps),
- The odd lines (from 3 13) are transition lines (for transitions and source connectors).
- Each step is located by a different number (0 127) in any order.
- Different graphs can be displayed on one page.

OR divergences

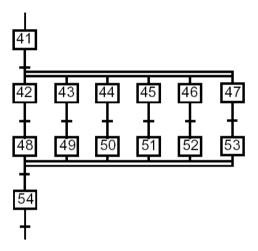
(OR convergences)



- The number of transitions upstream of a switching end (OR convergence) or downstream of a switching (OR divergence) must not exceed 11.
- Switching can be to the left or to the right.
- Switching must general finish with switching end.
- To avoid crossing several transitions at the same time, the associated transition conditions must be exclusive.

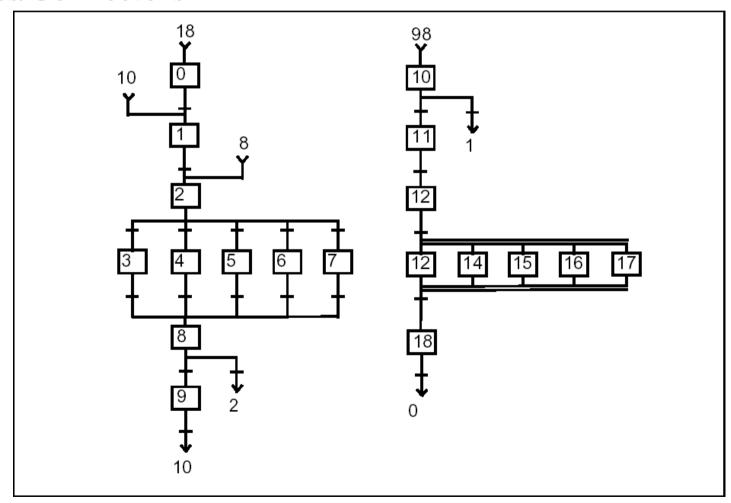
AND divergences

(AND Convergences)



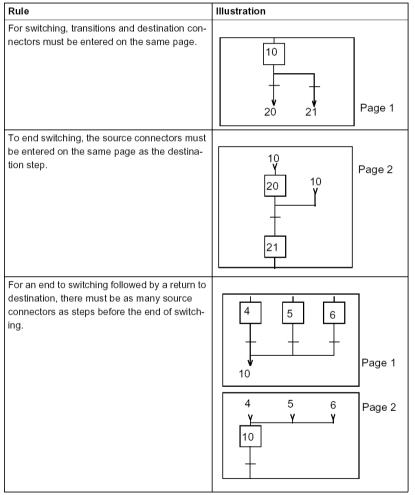
- The number of steps downstream from a simultaneous activation (AND divergence) or upstream from a simultaneous deactivation (AND convergence) must not exceed 11.
- Simultaneous activation of steps must usually end with a simultaneous deactivation of steps.
- Simultaneous activation is always shown from left to right.
- Simultaneous deactivation is always shown from right to left.

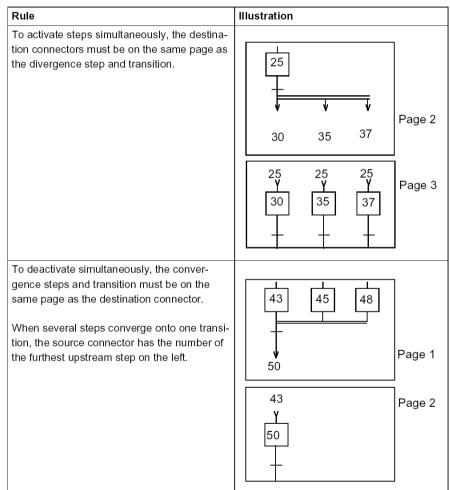
Arcs/Connectors



Rules for divergences and convergences:

OR AND





Programming Actions

The PL7 software allows three types of action:

- actions for activation: actions carried out once when the step with which they are associated passes from the inactive to the active state.
- actions for deactivation: actions carried out once when the step with which they are associated passes from the active to the inactive state.
- continuous actions: these actions are carried out for as long as the step with which they are associated is active.

Note: One action can include several programming elements (sequences or contact networks).

These actions are located in the following manner:

MAST - <Grafcet section name> - CHART (or MACROk)- PAGE n %Xi x with

x = P1 for Activation x = N1 Continuous x = P0 Deactivation

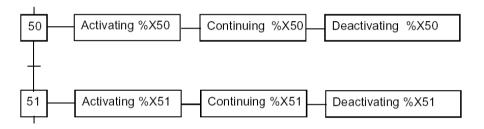
x = P1 for Activation, x = N1 Continuous, x = P0 Deactivation n = Page number

i = Step number

Example: MAST - Paint - CHART - PAGE 0 %X1 P1 Action for activating step 1 of page 0 of the Paint section

Programming Actions

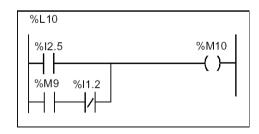
Example of execution of Actions



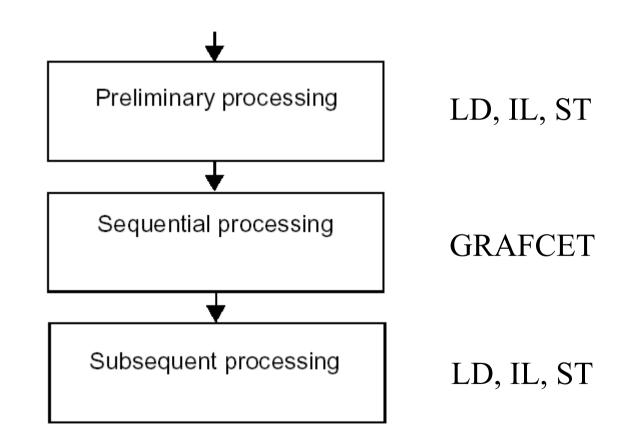
Example of Activation/deactivation

```
%L1
| %M25 SR4
| (C)
```

Example of continuous Action



GRAFCET Section Sctructure



GRAFCET Section Initialization

Initializing the Grafcet is done by the system bit %S21. Normally set at state 0, setting %S21 to 1 causes:

- active steps to deactivate,
- initial steps to activate.

The following table gives the different possibilities for setting to the system bit %S21 to 1 and 0.

Set to 1	Reset to 0
By setting %S0 to 1	By the system at the beginning of the pro-
By the user program	cess
By the terminal (in debugging or animation	By the user program
table)	By the terminal (in debugging or animation
	table)

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GRAFCET Section Reset

The system bit %S22 resets Grafcet to 0.

Normally set at 0, setting %S22 to 1 causes active steps in the whole of the sequential process to deactivate.

Note: The RESET_XIT function used to reinitialize via the program the step activity time of all the steps of the sequential processing. (See (See Reference Manual, Volume 2)).

The following table gives the different possibilities for setting to the system bit %S22 to 1 and 0.

Set to 1	Reset to 0
By the user programBy the terminal (in debugging or animation table)	By the system at the end of the sequential process